

General fractional multiparameter white noise theory and stochastic partial differential equations

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Abstract

We present a white noise calculus for d -parameter fractional Brownian motion $B_H(x, \omega)$; $x \in \mathbb{R}^d$, $\omega \in \Omega$ with general d -dimensional Hurst parameter $H = (H_1, \dots, H_d) \in (0, 1)^d$. As an illustration we solve the stochastic Poisson problem $\Delta U(x) = -W_H(x)$; $x \in D$, $U = 0$ on ∂D , where the potential $W_H(x)$ is d -parameter fractional white noise given by $W_H(x) = \frac{\partial^d B_H(x)}{\partial x_1 \dots \partial x_d}$, and $D \subset \mathbb{R}^d$ is a given bounded smooth domain. We also solve the linear stochastic heat equation $\frac{\partial U}{\partial t}(t, x) = \frac{1}{2} \Delta U(t, x) + W_H(t, x)$. For each equation we give sufficient conditions that the solutions $U(x)$ and $U(t, x)$, respectively, are square integrable random variables for all t, x .

1 Introduction

Recall that a *1-parameter fractional Brownian motion (fBm) with Hurst parameter* $H \in (0, 1)$ is a Gaussian stochastic process $B_H(t) = B_H(t, \omega)$; $t \in \mathbb{R}$, $\omega \in \Omega$ on a filtered probability space (Ω, \mathcal{F}, P) with the mean

$$(1.1) \quad E[B_H(t)] = B_H(0) = 0 \quad \text{for all } t \in \mathbb{R}$$

and covariance

$$(1.2) \quad E[B_H(s)B_H(t)] = \frac{1}{2} \{ |s|^{2H} + |t|^{2H} - |s-t|^{2H} \} \quad \text{for all } s, t \in \mathbb{R},$$

where E denotes expectation with respect to P . Note that if $H = \frac{1}{2}$ then $B_H(t)$ coincides with the classical Brownian motion.

For any $H \in (0, 1)$ the process $B_H(t)$ is *H-self-similar*, in the sense that the law of $\{B_H(\alpha t)\}_{t \in \mathbb{R}}$ is the same as the law of $\{\alpha^H B_H(t)\}_{t \in \mathbb{R}}$ for all $\alpha > 0$.

One of the reasons of the interest of fractional Brownian motion is that it can be used to model random phenomena with memory.

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For example, if $\frac{1}{2} < H < 1$ then $B_H(t)$ has a *long range dependence*, in the sense that

$$(1.3) \quad \sum_{n=1}^{\infty} E[B_H(1)(B_H(n+1) - B_H(n))] = \infty .$$

In this case the process is *persistent*, in the sense that high values have a tendency to be followed by an increase and low values by a decrease. This type of behavior is often observed in the levels of rivers, the characters of solar activity, the widths of consecutive annual rings and in the values of log returns in finance.

Similarly, if $0 < H < \frac{1}{2}$ then

$$(1.4) \quad E[B_H(1)(B_H(n+1) - B_H(n))] < 0$$

and the process is *anti-persistent*, in the sense that high values have a tendency to be followed by a decrease and low values by an increase. This feature makes the process natural for turbulence modeling. Indeed, fractional Brownian motion was first introduced by Kolmogorov in 1940 (see [Ko]), in connection with turbulence studies. In 1968 the process was reintroduced by Mandelbrot and van Ness [MvN], who gave the process its current name and suggested a number of applications.

For more information on 1-parameter fractional Brownian motion we refer to the book by Shiryaev [S] and the references therein.

There is a natural generalization of *fBm* to the multi-parameter case:

Fix a parameter dimension $d \in \mathbb{N}$ and a *Hurst parameter* $H = (H_1, H_2, \dots, H_d) \in (0, 1)^d$. Then we define the d -parameter fractional Brownian motion (or fractional Brownian *field*) $B_H(x_1, \dots, x_d)$; $x = (x_1, \dots, x_d) \in \mathbb{R}^d$ as the Gaussian process (field) with mean

$$(1.5) \quad E[B_H(x)] = B_H(0) = 0 \quad \text{for all } x \in \mathbb{R}^d$$

and covariance

$$(1.6) \quad E[B_H(x)B_H(y)] = \left(\frac{1}{2}\right)^d \prod_{i=1}^d (|x_i|^{2H_i} + |y_i|^{2H_i} - |x_i - y_i|^{2H_i}) \quad \text{for all } x, y \in \mathbb{R}^d.$$

These stochastic processes have been suggested in the modeling of the shape of mountain ranges ($d = 2$), the density of clouds ($d = 3$) and many other quantities. We refer to [AF] and [M] for more examples of modeling by multi-parameter *fBm*.

A stochastic calculus for 1-parameter *fBm* based on the Wick-Itô integral was constructed by [DHP] in the case $\frac{1}{2} < H < 1$. This was generalized to a fractional white noise calculus in [HØ], still for the case $\frac{1}{2} < H < 1$. Subsequently this 1-dimensional theory was extended (with certain restrictions) to be valid for all Hurst coefficients $H \in (0, 1)$ by [EvdH].

A multi-parameter fractional white noise calculus was developed in [H1], [H2] and subsequently in [HØZ1] and [ØZ], where it was used to solve certain stochastic partial differential equations driven by multi-parameter fractional white noise $W_H(x)$. However, the presentation in all these papers was based on the assumption that $H = (H_1, \dots, H_d) \in (\frac{1}{2}, 1)^d$.

The purpose of this paper is to present a multi-parameter fractional white noise theory valid for all Hurst parameters $H \in (0, 1)^d$. This is achieved in Section 2 and Section 3 by making a synthesis of the 1-parameter approach of [EvdH] and the multi-parameter

approach of [H1], [H2], [HØZ1] and [ØZ]. Then in Section 4 the theory is illustrated by solving explicitly the stochastic fractional Poisson equation

$$(1.7) \quad \Delta U(x) = -W_H(x); \quad x \in D \subset \mathbb{R}^d$$

$$(1.8) \quad U(x) = 0; \quad x \in \partial D$$

where D is a given bounded domain in \mathbb{R}^d with smooth boundary ∂D and $W_H(x) = \frac{\partial^d B_H(x)}{\partial x_1 \dots \partial x_d}$ is d -parameter fractional white noise.

In section 5 we solve the stochastic fractional heat equation

$$(1.9) \quad \frac{\partial U}{\partial t}(t, x) = \frac{1}{2} \Delta U(t, x) + W_H(t, x); \quad t \in (0, \infty), x \in D \subset \mathbb{R}^d$$

$$(1.10) \quad U(0, x) = 0; \quad x \in D$$

$$(1.11) \quad U(t, x) = 0 \quad t \geq 0, x \in \partial D.$$

For both equations we find sufficient conditions that the solution is a square integrable random variable.

2 Multiparameter fractional Brownian motion

We start by recalling the standard white noise construction of multiparameter *classical* Brownian motion $B(x); x \in \mathbb{R}^d$. We refer to [HKPS], [HØUZ] and [Ku] for more details.

Let $\mathcal{S} = \mathcal{S}(\mathbb{R}^d)$ be the Schwartz space of rapidly decreasing smooth functions on \mathbb{R}^d and let $\Omega := \mathcal{S}'(\mathbb{R}^d)$ be its dual, usually called *the space of tempered distributions*. By the Bochner-Minlos theorem there exists a probability measure μ on the Borel σ -algebra $\mathcal{B}(\Omega)$ such that

$$(2.1) \quad \int_{\Omega} e^{i\langle \omega, f \rangle} d\mu(\omega) = e^{-\frac{1}{2}\|f\|^2}; \quad f \in \mathcal{S}(\mathbb{R}^d)$$

where $\langle \omega, f \rangle = \omega(f)$ denotes the action of $\omega \in \Omega = \mathcal{S}'(\mathbb{R}^d)$ applied to $f \in \mathcal{S}(\mathbb{R}^d)$ and $\|f\|^2 = \int_{\mathbb{R}^d} |f(x)|^2 dx = \|f\|_{L^2(\mathbb{R}^d)}^2$. From (2.1) one can deduce that

$$(2.2) \quad E_{\mu}[\langle \omega, f \rangle] = 0 \quad \text{for all } f \in \mathcal{S}(\mathbb{R}^d)$$

where E_{μ} denotes the expectation with respect to μ . Moreover, we have the isometry

$$(2.3) \quad E_{\mu}[\langle \omega, f \rangle \langle \omega, g \rangle] = (f, g)_{L^2(\mathbb{R}^d)}; \quad f, g \in \mathcal{S}(\mathbb{R}^d).$$

Using this isometry we can extend the definition of $\langle \omega, f \rangle \in L^2(\mu)$ from $\mathcal{S}(\mathbb{R}^d)$ to $L^2(\mathbb{R}^d)$ as follows:

$$\langle \omega, f \rangle = \lim_{n \rightarrow \infty} \langle \omega, f_n \rangle \quad (\text{limit in } L^2(\mu))$$

when $f_n \in \mathcal{S}(\mathbb{R}^d)$, $f_n \rightarrow f \in L^2(\mathbb{R}^d)$ (limit in $L^2(\mathbb{R}^d)$).

In particular, we can now define, for $x = (x_1, \dots, x_d) \in \mathbb{R}^d$,

$$(2.4) \quad \tilde{B}(x) = \tilde{B}(x, \omega) = \langle \omega, \mathcal{X}_{[0, x]}(\cdot) \rangle; \quad \omega \in \Omega$$

where

$$(2.5) \quad \mathcal{X}_{[0,x]}(y) = \prod_{i=1}^d \mathcal{X}_{[0,x_i]}(y_i) \quad \text{for } y = (y_1, \dots, y_d) \in \mathbb{R}^d$$

and

$$(2.6) \quad \mathcal{X}_{[0,x_i]}(y_i) = \begin{cases} 1 & \text{if } 0 \leq y_i \leq x_i \\ -1 & \text{if } x_i \leq y_i \leq 0, \text{ except } x_i = y_i = 0 \\ 0 & \text{otherwise} \end{cases}$$

By Kolmogorov's continuity theorem the process $\{\tilde{B}(x)\}$ has a continuous version which we will denote by $\{B(x)\}$. By (2.1)–(2.3) it follows that $\{B(x)\}$ is a Gaussian process with mean

$$(2.7) \quad E[B(x)] = B(0) = 0$$

and covariance (using (2.3))

$$(2.8) \quad E[B(x)B(y)] = (\mathcal{X}_{[0,x]}, \mathcal{X}_{[0,y]})_{L^2(\mathbb{R}^d)} = \begin{cases} \prod_{i=1}^d x_i \wedge y_i & \text{if } x_i, y_i \geq 0 \text{ for all } i \\ \prod_{i=1}^d (-x_i) \wedge (-y_i) & \text{if } x_i, y_i \leq 0 \text{ for all } i \\ 0 & \text{otherwise} \end{cases}$$

Therefore $\{B(x)\}_{x \in \mathbb{R}^d}$ is a d -parameter Brownian motion.

We now use this Brownian motion to construct d -parameter *fractional* Brownian motion $B_H(x)$ for all Hurst parameters $H = (H_1, \dots, H_d) \in (0, 1)^d$. We do this by extending the procedure of [EvdH] to the d -dimensional case, as explained in [HØZ2]. For completeness we give the details.

For $0 < H_j < 1$ put

$$(2.9) \quad K_j = k_j \left[2\Gamma(H_j - \frac{1}{2}) \cos\left(\frac{\pi}{2}(H_j - \frac{1}{2})\right) \right]^{-1}, \quad k_j = \sin(\pi H_j) \Gamma(2H_j + 1)$$

and if $g \in \mathcal{S}(\mathbb{R}^d)$, $x = (x_1, \dots, x_d) \in \mathbb{R}^d$, define $m_j g(\cdot) : \mathbb{R}^d \rightarrow \mathbb{R}$ by

$$(2.10) \quad m_j g(x) = \begin{cases} K_j \int_{\mathbb{R}} \frac{g(x - t\varepsilon^{(j)}) - g(x)}{|t|^{\frac{3}{2} - H_j}} dt & \text{if } 0 < H_j < \frac{1}{2} \\ g(x) & \text{if } H_j = \frac{1}{2} \\ K_j \int_{\mathbb{R}} \frac{g(x_1, \dots, x_{j-1}, t, x_{j+1}, \dots, x_d) dt}{|x_j - t|^{\frac{3}{2} - H_j}} & \text{if } \frac{1}{2} < H_j < 1 \end{cases}$$

where

$$(2.11) \quad \varepsilon^{(j)} = (0, 0, \dots, 1, \dots, 0), \quad \text{the } j\text{'th unit vector.}$$

Then define

$$(2.12) \quad M_H f(x) = m_1(m_2(\dots(m_{d-1}(m_d f))\dots))(x); \quad f \in \mathcal{S}(\mathbb{R}^d).$$

Note that if $f(x) = f_1(x) \dots f_d(x_d) =: (f_1 \otimes \dots \otimes f_d)(x)$ is a tensor product, then

$$(2.13) \quad M_H f(x) = \prod_{j=1}^d (M_{H_j} f_j)(x_j)$$

where

$$(2.14) \quad M_{H_j} f_j(x_j) = \begin{cases} K_j \int_{\mathbb{R}} \frac{f_j(x_j-t) - f_j(x_j)}{|t|^{\frac{3}{2}-H_j}} dt & ; \quad 0 < H_j < \frac{1}{2} \\ f_j(x_j) & ; \quad H_j = \frac{1}{2} \\ K_j \int_{\mathbb{R}} \frac{f_j(t) dt}{|t-x_j|^{\frac{3}{2}-H_j}} & ; \quad \frac{1}{2} < H_j < 1 \end{cases}$$

Therefore, if

$$\mathcal{F}g(\xi) := \hat{g}(\xi) := \int_{\mathbb{R}^d} e^{-ix \cdot \xi} g(x) dx ; \quad \xi = (\xi_1, \dots, \xi_d) \in \mathbb{R}^d ,$$

denotes the Fourier transform of g , we have by (2.13)

$$(2.15) \quad \widehat{M_H f}(\xi) = \prod_{j=1}^d \widehat{M_{H_j} f_j}(\xi_j) = \prod_{j=1}^d k_j |\xi_j|^{\frac{1}{2}-H_j} \hat{f}_j(\xi_j)$$

and

$$(2.16) \quad \widehat{M_H^{-1} f}(\xi) = \left(\prod_{j=1}^d k_j |\xi_j|^{\frac{1}{2}-H_j} \right)^{-1} \hat{f}(\xi)$$

For more information about the operator M_H (for $d = 1$) see [EvdH, Appendix].

We now construct d -parameter fractional Brownian motion $B_H(x)$ with Hurst parameter $H = (H_1, \dots, H_d) \in (0, 1)^d$ as follows:

First define

$$(2.17) \quad \tilde{B}_H(x) = \tilde{B}_H(x, \omega) = \langle \omega, M_H(\mathcal{X}_{[0,x]}(\cdot)) \rangle$$

with $\mathcal{X}_{[0,x]}(\cdot)$ as in (2.5)–(2.6). Then $\tilde{B}_H(x)$ is a Gaussian process with mean

$$(2.18) \quad E[\tilde{B}_H(x)] = \tilde{B}_H(0) = 0$$

and covariance (using (2.13) and [EvdH, (1.13)])

$$(2.19) \quad \begin{aligned} E[\tilde{B}_H(x) \tilde{B}_H(y)] &= \int_{\mathbb{R}^d} M_H(\mathcal{X}_{[0,x]}(z)) M_H(\mathcal{X}_{[0,y]}(z)) dz \\ &= \int_{\mathbb{R}^d} \prod_{i=1}^d M_{H_i} \mathcal{X}_{[0,x_i]}(z_i) \cdot \prod_{j=1}^d M_{H_j} \mathcal{X}_{[0,y_j]}(z_j) dz_1 \dots dz_d \\ &= \prod_{j=1}^d \int_{\mathbb{R}} M_{H_j} \mathcal{X}_{[0,x_j]}(t) \cdot M_{H_j} \mathcal{X}_{[0,y_j]}(t) dt \\ &= \left(\frac{1}{2}\right)^d \prod_{j=1}^d \{ |x_j|^{2H_j} + |y_j|^{2H_j} - |x_j - y_j|^{2H_j} \} ; \quad x, y \in \mathbb{R}^d . \end{aligned}$$

By Kolmogorov's continuity theorem we get that $\{\tilde{B}_H(x)\}$ has a continuous version, which we denote by $\{B_H(x)\}$. From (2.18), (2.19) we conclude that $B_H(x)$ is a d -parameter fractional Brownian motion with Hurst parameter $H = (H_1, \dots, H_d) \in (0, 1)^d$.

If f is a simple deterministic function of the form

$$f(x) = \sum_{j=1}^N a_j \chi_{[0, y^{(j)}]}(x); \quad x \in \mathbb{R}^d$$

for some $a_j \in \mathbb{R}$, $y^{(j)} \in \mathbb{R}^d$ and $N \in \mathbb{N}$, then we define its integral with respect to B_H by

$$\int_{\mathbb{R}^d} f(x) dB_H(x) = \sum_{j=1}^N a_j B_H(y^{(j)}).$$

Note that by (2.16) this coincides with $\langle \omega, M_H f \rangle$, and we have the isometry

$$E\left[\left(\int_{\mathbb{R}^d} f(x) dB_H(x)\right)^2\right] = E[\langle \omega, M_H f \rangle^2] = \|M_H f\|_{L^2(\mathbb{R}^d)}^2.$$

We can extend the definition of this integral to all $g \in L_H^2(\mathbb{R}^d)$, where

$$(2.20) \quad L_H^2(\mathbb{R}^d) = \{g : \mathbb{R}^d \rightarrow \mathbb{R}; \|g\|_{L_H^2(\mathbb{R}^d)} := \|M_H g\|_{L^2(\mathbb{R}^d)} < \infty\}.$$

by setting

$$(2.21) \quad \int_{\mathbb{R}^d} g(x) dB_H(x) := \langle \omega, M_H g \rangle \quad \text{for all } g \in L_H^2(\mathbb{R}^d)$$

Moreover, if $f, g \in L_H^2(\mathbb{R}^d)$ then we have the isometry

$$(2.22) \quad \begin{aligned} E\left[\left(\int_{\mathbb{R}^d} f(x) dB_H(x)\right)\left(\int_{\mathbb{R}^d} g(x) dB_H(x)\right)\right] &= E[\langle \omega, M_H f \rangle \langle \omega, M_H g \rangle] \\ &= (M_H f, M_H g)_{L^2(\mathbb{R}^d)} = (f, g)_{L_H^2(\mathbb{R}^d)}. \end{aligned}$$

We mention that the space $L_H^2(\mathbb{R}^d)$ is not complete for $H > \frac{1}{2}$, see [H3], [PT] for more details.

3 Multiparameter fractional white noise calculus

With the processes $B_H(x)$ constructed in Section 2 as a starting point we proceed to develop a d -parameter white noise theory as in [HØZ1] and [ØZ], but modified according to the 1-parameter approach in [EvdH].

Let

$$h_n(t) = (-1)^n e^{\frac{t^2}{2}} \frac{d^n}{dt^n} \left(e^{-\frac{t^2}{2}}\right); \quad n = 0, 1, 2, \dots; \quad t \in \mathbb{R}$$

be the *Hermite polynomials* and let

$$(3.1) \quad \tilde{h}_n(t) = \pi^{-\frac{1}{4}} ((n-1)!)^{-\frac{1}{2}} h_{n-1}(\sqrt{2}t) e^{-\frac{t^2}{2}}; \quad n = 1, 2, \dots; \quad t \in \mathbb{R}$$

be the *Hermite functions*.

If $\alpha = (\alpha_1, \dots, \alpha_d) \in \mathbb{N}^d$ (with $\mathbb{N} = \{1, 2, \dots\}$) and $x = (x_1, \dots, x_d) \in \mathbb{R}^d$ define

$$(3.2) \quad \eta_\alpha(x) = \tilde{h}_{\alpha_1}(x_1) \dots \tilde{h}_{\alpha_d}(x_d) = (\tilde{h}_{\alpha_1} \otimes \dots \otimes \tilde{h}_{\alpha_d})(x)$$

and

$$(3.3) \quad e_\alpha(x) = (M_{H\alpha_1}^{-1} \tilde{h}_{\alpha_1})(x_1) \dots (M_{H\alpha_d}^{-1} \tilde{h}_{\alpha_d})(x_d) = (M_H^{-1} \eta_\alpha)(x).$$

Let $\{\alpha^{(i)}\}_{i=1}^\infty$ be a fixed ordering of \mathbb{N}^d with the property that, with $|\alpha^{(i)}| = \alpha_1^{(i)} + \dots + \alpha_d^{(i)}$,

$$(3.4) \quad i < j \Rightarrow |\alpha^{(i)}| \leq |\alpha^{(j)}|.$$

Note that this implies that there exists a constant $C < \infty$ such that

$$(3.5) \quad |\alpha^{(k)}| \leq Ck \quad \text{for all } k.$$

With a slight abuse of notation let us write

$$(3.6) \quad \eta_n(x) := \eta_{\alpha^{(n)}}(x) = M_H e_n(x)$$

and

$$(3.7) \quad e_n(x) := e_{\alpha^{(n)}}(x) = M_H^{-1} \eta_n(x); \quad n = 1, 2, \dots$$

Now let $\mathcal{J} = (\mathbb{N}_0^{\mathbb{N}})_c$ denote the set of all finite sequences $\alpha = (\alpha_1, \dots, \alpha_m)$ with $\alpha_j \in \mathbb{N}_0 = \mathbb{N} \cup \{0\}$, $m = 1, 2, \dots$. Then if $\alpha = (\alpha_1, \dots, \alpha_m) \in \mathcal{J}$ we define

$$(3.8) \quad \mathcal{H}_\alpha(\omega) = h_{\alpha_1}(\langle \omega, \eta_1 \rangle) \dots h_{\alpha_m}(\langle \omega, \eta_m \rangle)$$

In particular, note that by (2.21) we have

$$(3.9) \quad \begin{aligned} \mathcal{H}_{\varepsilon^{(i)}}(\omega) &= h_1(\langle \omega, \eta_i \rangle) = \langle \omega, \eta_i \rangle = \int_{\mathbb{R}^d} \eta_i(x) dB(x) \\ &= \int_{\mathbb{R}^d} M_H e_i(x) dB(x) = \langle \omega, M_H e_i \rangle = \int_{\mathbb{R}^d} e_i(x) dB_H(x); \quad i = 1, 2, \dots \end{aligned}$$

We recall the following well-known result:

Theorem 3.1 (The chaos expansion theorem)

Every $F \in L^2(\mu)$ can be written as the form

$$(3.10) \quad F(\omega) = \sum_{\alpha \in \mathcal{J}} c_\alpha \mathcal{H}_\alpha(\omega)$$

where $c_\alpha \in \mathbb{R}$. Moreover, we have the isometry

$$(3.11) \quad \|F\|_{L^2(\mu)}^2 = \sum_{\alpha \in \mathcal{J}} \alpha! c_\alpha^2$$

where $\alpha! = \alpha_1! \alpha_2! \dots \alpha_m!$ if $\alpha = (\alpha_1, \dots, \alpha_m)$.

Note that if $f \in \mathcal{S}(\mathbb{R}^d)$ then $M_H f \in L^2(\mathbb{R}^d)$. Moreover, if $f, g \in \mathcal{S}(\mathbb{R}^d)$ then

$$(3.12) \quad (g, M_H f)_{L^2(\mathbb{R}^d)} = (\hat{g}, \widehat{M_H f})_{L^2(\mathbb{R}^d)} = (M_H g, f)_{L^2(\mathbb{R}^d)} .$$

Therefore, since the action of $\omega \in \Omega = \mathcal{S}'(\mathbb{R}^d)$ extends to $L^2(\mathbb{R}^d)$, we can extend the definition of the operator M_H from $\mathcal{S}(\mathbb{R}^d)$ to $\Omega = \mathcal{S}'(\mathbb{R}^d)$ by setting

$$(3.13) \quad \langle M_H \omega, f \rangle = \langle \omega, M_H f \rangle ; \quad f \in \mathcal{S}(\mathbb{R}), \quad \omega \in \mathcal{S}'(\mathbb{R}) .$$

We now define

$$(3.14) \quad L_H^2(\mu) = \{G : \Omega \rightarrow \mathbb{R}, G \circ M_H \in L^2(\mu)\}$$

and

$$(3.15) \quad \|G\|_{L_H^2(\mu)}^2 = \|G \circ M_H\|_{L^2(\mu)}^2 \quad \text{for } G \in L_H^2(\mu) .$$

Example 3.2 The chaos expansion of classical Brownian motion $B(x) \in L^2(\mu)$ is

$$(3.16) \quad B(x) = \langle \omega, \mathcal{X}_{[0,x]} \rangle = \sum_{k=1}^{\infty} (\mathcal{X}_{[0,x]}, \eta_k)_{L^2(\mathbb{R}^d)} \langle \omega, \eta_k \rangle = \sum_{k=1}^{\infty} \left(\int_{-\infty}^x \eta_k(y) dy \right) \cdot \mathcal{H}_{\varepsilon^{(k)}}(\omega) ,$$

where in general we put

$$(3.17) \quad \int_{-\infty}^x g(y) dy = \int_{-\infty}^{x_d} \cdots \int_{-\infty}^{x_1} g(y) dy_1 \dots dy_d ; \quad x = (x_1, \dots, x_d) \in \mathbb{R}^d .$$

Hence by (2.17) the chaos expansion of fractional Brownian motion $B_H(x) \in L_H^2(\mu)$ is

$$(3.18) \quad \begin{aligned} B_H(x) &= \langle \omega, M_H \mathcal{X}_{[0,x]} \rangle \\ &= \sum_{k=1}^{\infty} (M_H \mathcal{X}_{[0,x]}, \eta_k)_{L^2(\mathbb{R}^d)} \langle \omega, \eta_k \rangle = \sum_{k=1}^{\infty} (\mathcal{X}_{[0,x]}, M_H \eta_k)_{L^2(\mathbb{R}^d)} \mathcal{H}_{\varepsilon^{(k)}}(\omega) \end{aligned}$$

$$(3.19) \quad = \sum_{k=1}^{\infty} \left(\int_{-\infty}^x M_H \eta_k(y) dy \right) \mathcal{H}_{\varepsilon^{(k)}}(\omega) .$$

Similarly, if $f \in L_H^2(\mathbb{R}^d)$ then by (2.21)

$$(3.20) \quad \int_{\mathbb{R}} f(x) dB_H(x) = \langle \omega, M_H f \rangle = \langle M_H \omega, f \rangle = \sum_{k=1}^{\infty} (M_H \eta_k, f)_{L^2(\mathbb{R}^d)} \mathcal{H}_{\varepsilon^{(k)}}(\omega) .$$

Next we define the d -parameter Hida test function and distribution spaces (\mathcal{S}) and $(\mathcal{S})^*$, respectively:

Definition 3.3

a) For $k = 1, 2, \dots$ let $(\mathcal{S})^{(k)}$ be the set of $G \in L^2(\mu)$ with expansion

$$G(\omega) = \sum_{\alpha} c_{\alpha} \mathcal{H}_{\alpha}(\omega)$$

such that

$$(3.21) \quad \|G\|_{(\mathcal{S})^{(k)}}^2 := \sum_{\alpha} \alpha! c_{\alpha}^2 (2\mathbb{N})^{\alpha k} < \infty$$

where

$$(3.22) \quad (2\mathbb{N})^{\beta} = (2 \cdot 1)^{\beta_1} (2 \cdot 2)^{\beta_2} \dots (2m)^{\beta_m} \quad \text{if } \beta = (\beta_1, \dots, \beta_m) \in \mathcal{J}$$

The space of *Hida test functions*, (\mathcal{S}) , is defined by

$$(3.23) \quad (\mathcal{S}) = \bigcap_{k=1}^{\infty} (\mathcal{S})^{(k)}, \quad \text{equipped with the projective topology.}$$

b) For $q = 1, 2, \dots$ let $(\mathcal{S})^{(-q)}$ be the set of all formal expansions

$$G = \sum_{\alpha} c_{\alpha} \mathcal{H}_{\alpha}(\omega)$$

such that

$$(3.24) \quad \|G\|_{(\mathcal{S})^{(-q)}} := \sum_{\alpha} \alpha! c_{\alpha}^2 (2\mathbb{N})^{-q\alpha} < \infty .$$

The space of *Hida distributions*, $(\mathcal{S})^*$, is defined by

$$(3.25) \quad (\mathcal{S})^* = \bigcup_{q=1}^{\infty} (\mathcal{S})^{(-q)}, \quad \text{equipped with the inductive topology.}$$

Note that with this definition we have

$$(3.26) \quad (\mathcal{S}) \subset L^2(\mu) \subset (\mathcal{S})^* .$$

Example 3.4 Define *fractional white noise*, $W_H(x)$, by

$$(3.27) \quad W_H(x) = \sum_{k=1}^{\infty} M_H \eta_k(x) \mathcal{H}_{\varepsilon^{(k)}}(\omega) ; \quad x \in \mathbb{R}^d .$$

Then $W_H(x) \in (\mathcal{S})^*$ because in this case, by (3.3) and (3.5),

$$\begin{aligned} \sum_{\alpha} \alpha! c_{\alpha}^2 (2\mathbb{N})^{-q\alpha} &= \sum_{k=1}^{\infty} (M_H \eta_k)^2(x) (2\mathbb{N})^{-q\varepsilon^{(k)}} \\ &= \sum_{k=1}^{\infty} (M_{H_{\alpha_1^{(k)}}} \tilde{h}_{\alpha_1^{(k)}})^2(x_1) \dots (M_{H_{\alpha_d^{(k)}}} \tilde{h}_{\alpha_d^{(k)}})^2(x_d) (2k)^{-q} \\ &\leq \sum_{k=1}^{\infty} C_1 \left(\prod_{j=1}^d (\alpha_j^{(k)})^{\frac{2}{3} - \frac{H_j}{2}} \right)^2 (2k)^{-q} \leq C_1 \sum_{k=1}^{\infty} (2k)^{\frac{4d}{3} - q} < \infty \end{aligned}$$

for $q > \frac{4d}{3} + 1$ (C_1 is a constant). Here we have used the estimate

$$(3.28) \quad |M_{H_j} \tilde{h}_n(t)| \leq C_2 n^{\frac{2}{3} - \frac{H_j}{2}} \quad \text{for all } t \text{ (} C_2 \text{ constant)}$$

from Section 3 of [EvdH].

Note that from (3.27) and (3.19) we have that

$$(3.29) \quad \frac{\partial^d}{\partial x_1 \dots \partial x_d} B_H(x) = W_H(x) \quad (\text{in } (\mathcal{S})^* \text{ for all } x \in \mathbb{R}^d).$$

This justifies the name *fractional white noise* for the process $W_H(x)$.

Choose $g \in \mathcal{S}(\mathbb{R}^d)$ and let $m_j g$ be as in (2.10). We establish a useful formula for the $L^2(\mathbb{R})$ norm of $m_j g$.

Theorem 3.5 *Let f and g be elements in $\mathcal{S}(\mathbb{R})$ (the space of rapidly decreasing functions). If $0 < H_j < \frac{1}{2}$, then there is a constant κ such that*

$$(3.30) \quad \int_{\mathbb{R}} m_j f(x) m_j g(x) dx = \kappa \int_{\mathbb{R}} \int_{\mathbb{R}} |x - y|^{2H_j} f'(x) g'(y) dx dy.$$

Proof. From (2.15) we have

$$\mathcal{F}(m_j f)(\xi) = K_j |\xi|^{\frac{1}{2} - H_j} \hat{f}(\xi).$$

Thus

$$\int_{\mathbb{R}} m_j f(x) m_j g(x) dx = \frac{1}{2\pi} K_j^2 \int_{\mathbb{R}} |\xi|^{1-2H_j} \bar{\hat{f}}(\xi) \hat{g}(\xi) d\xi.$$

For $\alpha > 0$ define

$$I^\alpha \phi(x) = \gamma_\alpha \int_{\mathbb{R}} \frac{\phi(t)}{|t - x|^{1-\alpha}} dt,$$

where $\gamma_\alpha = 2\Gamma(\alpha) \cos(\alpha\pi/2)$. By [SKM], we have

$$\mathcal{F}(I^\alpha \phi)(\xi) = |\xi|^{-\alpha} \hat{\phi}(\xi).$$

Therefore,

$$\int_{\mathbb{R}} f'(x) I^\alpha g'(x) dx = \frac{1}{2\pi} \int_{\mathbb{R}} |\xi|^{2-\alpha} \bar{\hat{f}}(\xi) \hat{g}(\xi) d\xi.$$

Hence,

$$\int_{\mathbb{R}} m_j f(x) m_j g(x) dx = K_j^2 \int_{\mathbb{R}} f'(x) I^\alpha g'(x) dx$$

if $1 - 2H_j = 2 - \alpha$. That is

$$\alpha = 1 + 2H_j.$$

When the above identity is true, we have

$$\int_{\mathbb{R}} f'(x) I^\alpha g'(x) dx = \kappa \int_{\mathbb{R}^2} |x - y|^{2H_j} f'(x) g'(y) dx dy,$$

where

$$\kappa = \gamma_\alpha K_j^2.$$

Remark It is easy to extend the identity to more general functions.

4 The stochastic fractional Poisson equation

We now illustrate the use of the theory above by solving the Poisson equation with fractional white noise heat source:

Let $D \subset \mathbb{R}^d$ be a given bounded domain with smooth (C^∞) boundary. We want to find $U(\cdot) : \bar{D} \rightarrow (\mathcal{S})^*$ such that

$$(4.1) \quad \Delta U(x) = -W_H(x) \quad \text{for } x \in D$$

$$(4.2) \quad U(x) = 0 \quad \text{for } x \in \partial D$$

(where $\Delta = \frac{1}{2} \sum_{i=1}^d \frac{\partial^2}{\partial x_i^2}$ is the Laplacian operator) and such that U is continuous on the closure \bar{D} of D .

From classical potential theory we are led to the solution candidate

$$(4.3) \quad U(x) = \int_D G(x, y) W_H(y) dy = \int_D G(x, y) dB_H(y)$$

where G is the classical Green function for the Dirichlet Laplacian.

We first verify that $U(x) \in (\mathcal{S})^*$ for all x . To this end, consider the expansion of $U(x)$:

$$(4.4) \quad \begin{aligned} U(x) &= \int_D G(x, y) \sum_{k=1}^{\infty} M_H \eta_k(y) \mathcal{H}_{\varepsilon^{(k)}}(\omega) dy \\ &= \sum_{k=1}^{\infty} a_k(x) \mathcal{H}_{\varepsilon^{(k)}}(\omega), \quad \text{where} \\ a_k(x) &= \int_D G(x, y) M_H \eta_k(y) dy . \end{aligned}$$

By the estimate (3.28) we have

$$(4.5) \quad |a_k(x)| \leq C_3 k^{\frac{2d}{3}} \int_D G(x, y) dy \leq C_4 k^{\frac{2d}{3}},$$

and therefore

$$\sum_{k=1}^{\infty} a_k^2(x) (2\mathbb{N})^{-q\varepsilon_k} \leq C_4^2 \sum_{k=1}^{\infty} (2k)^{\frac{4d}{3}} (2k)^{-q} < \infty$$

for $q > \frac{4d}{3} + 1$.

This proves that $U(x) \in (\mathcal{S})^*$ and the same estimate gives that $U : \bar{D} \rightarrow (\mathcal{S})^*$ is continuous.

The proof that $\Delta U(x) = -W_H(x)$ is identical to the proof given in [HØZ1, Section 3] and is omitted. We conclude that $U(x)$ given by (4.3) is indeed the solution of (4.1)–(4.2).

Thus we have:

Theorem 4.1 *Let $H = (H_1, \dots, H_d) \in (0, 1)^d$. The stochastic fractional Poisson equation (4.1)–(4.2) has a unique solution $U(x) \in (\mathcal{S})^*$ given by*

$$(4.6) \quad U(x) = \int_D G(x, y) dB_H(y) ,$$

where $G(x, y)$ is the classical Green function for the Laplacian.

Next we discuss when this solution $U(x)$ belongs to $L^2(\mu)$. In [HØZ1] it is proved that if

$$(4.7) \quad \frac{1}{2} < H_i < 1 \quad \text{for all } i$$

and

$$(4.8) \quad \sum_{i=1}^d H_i > d - 2$$

then $U(x) \in L^2(\mu)$ for all x .

We will show that condition (4.8) is sufficient to have $U(x) \in L^2(\mu)$ also without condition (4.7):

Theorem 4.2 *Let $H = (H_1, \dots, H_d) \in (0, 1)^d$ and $\mathbb{H} := \{i, H_i < 1/2\}$. Suppose that $\#\mathbb{H} \leq 1$ and*

$$(4.9) \quad \sum_{i \in \mathbb{H}} H_i > d - 2.$$

Then the solution $U(x)$ given by (4.6) belongs to $L^2(\mu)$ for all x .

Proof. By (4.3) and (2.22) we have

$$(4.10) \quad \begin{aligned} E[U^2(x)] &= (G(x, \cdot), G(x, \cdot))_{L^2_H(\mathbb{R}^d)} \\ &= (M_H G(x, \cdot), M_H G(x, \cdot))_{L^2(\mathbb{R}^d)} = \int_{\mathbb{R}^d} (M_H G(x, y))^2 dy, \end{aligned}$$

where the operator M_H acts on y , and we have extended the function $G(x, \cdot)$ and $M_H G(x, \cdot)$ to \mathbb{R}^d by defining it to be zero outside D

Without loss of generality we can assume that

$$(4.11) \quad H_1 < \frac{1}{2} \quad \text{and} \quad H_i > \frac{1}{2} \quad \text{for } i > 1.$$

Since ∂D is smooth there exists a constant C such that

$$(4.12) \quad \left| \frac{\partial^k}{\partial y_1 \dots \partial y_k} G(x, y) \right| \leq C \frac{\prod_{i=1}^k |x_i - y_i|}{|x - y|^{d+2k-2}}.$$

Recall that if $\frac{1}{2} < H_j < 1$,

$$\int_{\mathbb{R}^d} m_j f(x)^2 dx = c_j \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} f(x) |x - y|^{2H_j-2} f(y) dx dy$$

Hence by (4.10) and Theorem 3.8

$$(4.13) \quad E[U^2(x)] \leq C \int_D \int_D \frac{|x_1 - y_1|}{|x - y|^d} \phi(y, z) \frac{|x_1 - z_1|}{|x - z|^d} dy dz,$$

where

$$(4.14) \quad \phi(y, z) = |y_1 - z_1|^{2H_1} \prod_{i=2}^d |y_i - z_i|^{2H_i-2}.$$

Let $z' = x - z$ and $y' = x - y$. Since D is bounded there exists a positive constant R such that, using (4.13),

$$\begin{aligned}
E[U^2(x)] &\leq C \int_{-R}^R \cdots \int_{-R}^R \frac{|y'_1|}{|y'|^d} \phi(y', z') \frac{|z'_1|}{|z'|^d} dy' dz' \\
(4.15) \quad &= C \int_{-R}^R \cdots \int_{-R}^R \frac{|y_1||z_1||y_1 - z_1|^{2H_1} \prod_{i=2}^d |y_i - z_i|^{2H_i-2}}{|y|^d |z|^d} dy dz
\end{aligned}$$

Next we are going to show that the integral above is finite.

For notational simplicity, we assume that $R = 1$. For any $a > 0, b > 0, d > 0$, we claim that there is a constant c , independent of a and b such that

$$(4.16) \quad \int_{-1}^1 \int_{-1}^1 \frac{|y||z||y-z|^{2H_1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \leq c \frac{a^{H_1} + b^{H_1}}{a^{d/2-1}b^{d/2-1}}$$

Indeed,

$$\begin{aligned}
&\int_{-1}^1 \int_{-1}^1 \frac{|y||z||y-z|^{2H_1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \\
&\leq c \left\{ \int_{-1}^1 dy \int_{-1}^1 \frac{|y||z|(|y|^{2H_1} + |z|^{2H_1})}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dz \right\} \\
&\leq c \left\{ \int_0^1 dy \frac{y^{2H_1+1}}{(y^2+a)^{d/2}} \int_0^1 \frac{z}{(z^2+b)^{d/2}} dz + \int_0^1 dz \frac{z^{2H_1+1}}{(z^2+b)^{d/2}} \int_0^1 \frac{y}{(y^2+a)^{d/2}} dy \right\} \\
&\leq c \int_0^1 \frac{y^{2H_1+1}}{(y^2+a)^{d/2}} [b^{1-d/2} - (1+b)^{1-d/2}] dy + c \int_0^1 \frac{z^{2H_1+1}}{(z^2+b)^{d/2}} [a^{1-d/2} - (1+a)^{1-d/2}] dz \\
&\leq cb^{1-d/2} \int_0^1 \frac{y}{(y^2+a)^{d/2-H_1}} dy + ca^{1-d/2} \int_0^1 \frac{z}{(z^2+b)^{d/2-H_1}} dz \\
&\leq cb^{1-d/2} a^{1-d/2+H_1} + a^{1-d/2} b^{1-d/2+H_1} = c \frac{a^{H_1} + b^{H_1}}{a^{d/2-1}b^{d/2-1}}.
\end{aligned}$$

Applying (4.16) for $a = \sum_{i=2}^d y_i^2, b = \sum_{i=2}^d z_i^2$, we have

$$\begin{aligned}
&\int_{-1}^1 \cdots \int_{-1}^1 \frac{|y_1||z_1||y_1 - z_1|^{2H_1} \prod_{i=2}^d |y_i - z_i|^{2H_i-2}}{|y|^d |z|^d} dy dz \\
&= \int_{-1}^1 \cdots \int_{-1}^1 \prod_{i=2}^d |y_i - z_i|^{2H_i-2} dy_2 \cdots dy_d dz_2 \cdots dz_d \int_{-1}^1 \int_{-1}^1 \frac{|y_1||z_1||y_1 - z_1|^{2H_1}}{|y|^d |z|^d} dy_1 dz_1 \\
&\leq c \int_{-1}^1 \cdots \int_{-1}^1 \frac{\prod_{i=2}^d |y_i - z_i|^{2H_i-2} [(\sum_{i=2}^d y_i^2)^{H_1} + (\sum_{i=2}^d z_i^2)^{H_1}]}{(\sum_{i=2}^d y_i^2)^{d/2-1} (\sum_{i=2}^d z_i^2)^{d/2-1}} dy_2 \cdots dy_d dz_2 \cdots dz_d \\
&= \int_{-1}^1 \cdots \int_{-1}^1 \frac{\prod_{i=2}^d |y_i - z_i|^{2H_i-2}}{(\sum_{i=2}^d y_i^2)^{d/2-1-H_1} (\sum_{i=2}^d z_i^2)^{d/2-1}} dy_2 \cdots dy_d dz_2 \cdots dz_d
\end{aligned}$$

$$\begin{aligned}
& + \int_{-1}^1 \cdots \int_{-1}^1 \frac{\prod_{i=2}^d |y_i - z_i|^{2H_i-2}}{(\sum_{i=2}^d y_i^2)^{d/2-1} (\sum_{i=2}^d z_i^2)^{d/2-1-H_1}} dy_2 \cdots dy_d dz_2 \cdots dz_d \\
& =: I + II.
\end{aligned}$$

We now prove both I and II are finite. By symmetry, we only look at I .

For any choice of positive numbers $\alpha_i > 0$ with $\sum_{i=2}^d \alpha_i = 1$ and positive numbers $\beta_i > 0$ with $\sum_{i=2}^d \beta_i = 1$, we have

$$(4.17) \quad I \leq \int_{-1}^1 \cdots \int_{-1}^1 \frac{\prod_{i=2}^d |y_i - z_i|^{2H_i-2}}{\prod_{i=2}^d |y_i|^{\alpha_i(d-2-2H_1)} |z_i|^{\beta_i(d-2)}} dy_2 \cdots dy_d dz_2 \cdots dz_d$$

So, I is finite if the following conditions are met:

$$(4.18) \quad \begin{aligned} \alpha_i(d-2-2H_1) &< 1, & i = 2, \dots, d \\ \beta_i(d-2) &< 1, & i = 2, \dots, d \\ \alpha_i(d-2-2H_1) + \beta_i(d-2) - 2H_i + 2 &< 2, & i = 2, \dots, d \end{aligned}$$

Adding these inequalities in (4.18), we see that it is sufficient to have

$$2(d-2) - 2H_1 < \sum_{i=2}^d 2H_i,$$

namely,

$$\sum_{i=1}^d H_i > d - 2$$

This completes the proof. □

Remark It is natural to ask if condition (4.9) is also *necessary* to have $U(x) \in L^2(\mu)$. Now we give a discussion.

We need the following: For any $a > 0, b > 0, d > 0$ (a and b bounded), there is a constant c , independent of a and b such that

$$(4.19) \quad \int_{-1}^1 \int_{-1}^1 \frac{|y||z||y-z|^{2H_1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \geq c \frac{a^{H_1}}{a^{d/2-1}b^{d/2-1}}$$

and

$$(4.20) \quad \int_{-1}^1 \int_{-1}^1 \frac{|y||z||y-z|^{2H_1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \geq c \frac{b^{H_1}}{a^{d/2-1}b^{d/2-1}}$$

In fact,

$$\begin{aligned}
& \int_{-1}^1 \int_{-1}^1 \frac{|y||z||y-z|^{2H_1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \\
& \geq \int_0^1 \int_{-1}^1 \frac{y|z||y-z|^{2H_1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \\
& \geq \int_0^1 \int_{-1}^0 \frac{y|z|^{2H_1+1}}{(y^2+a)^{d/2}(z^2+b)^{d/2}} dy dz \\
& \geq c \int_0^1 dy \frac{y}{(y^2+a)^{d/2}} \int_0^1 \frac{z^{2H_1+1}}{(z^2+b)^{d/2}} dz \\
& = ca^{-\frac{d}{2}+1} \int_0^{\frac{1}{\sqrt{a}}} \frac{u}{(u^2+1)^{d/2}} du b^{-\frac{d}{2}+1+H_1} \int_0^{\frac{1}{\sqrt{b}}} \frac{v^{2H_1+1}}{(v^2+1)^{d/2}} dv \\
& \geq c \frac{b^{H_1}}{a^{d/2-1}b^{d/2-1}}.
\end{aligned}$$

This proves (4.20). In a similar way we can prove (4.19).

Let us consider (4.15) in the case when $d = k = 2$, namely,

$$(4.21) \quad \int_{-1}^1 \dots \int_{-1}^1 \frac{|y_1||z_1||y_1-z_1|^{2H_1}}{|y|^{d+2}} \frac{|y_2||z_2||y_2-z_2|^{2H_2}}{|z|^{d+2}} dy dz,$$

where $0 < H_1, H_2 < 1/2$. Applying (4.20) for $a = y_2^2, b = z_2^2$, we have

$$\int_{-1}^1 \dots \int_{-1}^1 \frac{|y_1||z_1||y_1-z_1|^{2H_1}}{|y|^{d+2}} \frac{|y_2||z_2||y_2-z_2|^{2H_2}}{|z|^{d+2}} dy dz \geq c \int_{-1}^1 \int_{-1}^1 \frac{z_2^{H_1}|y_2||z_2||y_2-z_2|^{2H_2}}{y_2^2 z_2^2} dy_2 dz_2$$

which is divergent. Thus we conjecture that $U(t, x)$ is in L^2 only if one or less Hurst exponent is less than $1/2$.

5 The linear heat equation driven by fractional white noise

In this section we consider the linear stochastic fractional heat equation

$$(5.1) \quad \frac{\partial U}{\partial t}(t, x) = \frac{1}{2} \Delta U(t, x) + W_H(t, x); \quad t \in (0, \infty), \quad x \in D \subset \mathbb{R}^d$$

$$(5.2) \quad U(0, x) = 0; \quad x \in D$$

$$(5.3) \quad U(t, x) = 0; \quad t \geq 0, \quad x \in \partial D$$

Here $W_H(t, x)$ is the fractional white noise with Hurst parameter $H = (H_0, H_1, \dots, H_d) \in (0, 1)^{d+1}$, $\Delta = \sum_{i=1}^d \frac{\partial^2}{\partial x_i^2}$ is the Laplace operator, $D \subset \mathbb{R}^d$ is a bounded open set with smooth boundary ∂D . We are looking for a solution $U : [0, \infty) \times \bar{D} \rightarrow (\mathcal{S})^*$ which is continuously differentiable in (t, x) and twice continuously differentiable in x , i.e. belongs to $C^{1,2}((0, \infty) \times D; (\mathcal{S})^*)$, and which satisfies (5.1) in the strong sense (as an $(\mathcal{S})^*$ -valued function).

Based on the corresponding solution in the deterministic case (with $W_H(t, x)$ replaced by a bounded deterministic function) it is natural to guess that the solution will be

$$(5.4) \quad U(t, x) = \int_0^t \int_D W_H(s, y) G_{t-s}(x, y) dy ds$$

where $G_{t-s}(x, y)$ is the Green function for the heat operator $\frac{\partial}{\partial t} - \frac{1}{2}\Delta$. It is well-known [D] that G is smooth in $(0, \infty) \times D$ and that

$$(5.5) \quad |G_u(x, y)| \sim u^{-d/2} \exp\left(-\frac{|x-y|^2}{\delta u}\right) \quad \text{in } (0, \infty) \times D,$$

and

$$(5.6) \quad \left| \frac{\partial G_u(x, y)}{\partial y_i} \right| \sim u^{-d/2-1} |x_i - y_i| \exp\left(-\frac{|x-y|^2}{\delta u}\right) \quad \text{in } (0, \infty) \times D,$$

where the notation $X \sim Y$ means that

$$\frac{1}{C}X \leq Y \leq CX \quad \text{in } (0, \infty) \times D,$$

for some positive constant $C < \infty$ depending only on D .

We use this to verify that $U(t, x) \in (\mathcal{S})^*$ for all $(t, x) \in [0, \infty) \times \bar{D}$:

Using (3.27) we see that the expansion of $U(t, x)$ is

$$(5.7) \quad \begin{aligned} U(t, x) &= \int_0^t \int_D G_{t-s}(x, y) \sum_{k=1}^{\infty} M_H \eta_k(s, y) \mathcal{H}_{\varepsilon(k)}(\omega) dy ds \\ &= \sum_{k=1}^{\infty} b_k(t, x) \mathcal{H}_{\varepsilon(k)}(\omega), \end{aligned}$$

where

$$(5.8) \quad b_k(t, x) = b_{\varepsilon(k)}(t, x) = \int_0^t \int_D G_{t-s}(x, y) M_H \eta_k(s, y) dy ds$$

In the following C denotes a generic constant, not necessarily the same from place to place. From (3.28) we obtain that

$$(5.9) \quad \begin{aligned} |b_k(t, x)| &\leq C k^{\frac{2(d+1)}{3}} \int_0^t \int_D G_{t-s}(x, y) dy ds \\ &= C k^{\frac{2(d+1)}{3}} t \end{aligned}$$

Therefore

$$(5.10) \quad \sum_{k=1}^{\infty} b_k^2(t, x) (2\mathbb{N})^{-q\epsilon^{(k)}} \leq C(t) \sum_{k=1}^{\infty} k^{\frac{4(d+1)}{3}} (2k)^{-q} < \infty$$

for $q > \frac{4(d+1)}{3} + 1$.

Hence $U(t, x) \in (\mathcal{S})^{-q^*}$ for all $q > \frac{4(d+1)}{3} + 1$, for all t, x .

In fact, this estimate also shows that $U(t, x)$ is uniformly continuous as a function from $[0, T] \times D$ into $(\mathcal{S})^*$ for any $T < \infty$. Moreover, by the properties of $G_{t-s}(x, y)$ we get from (5.4) that

$$(5.11) \quad \begin{aligned} \frac{\partial U}{\partial t}(t, x) - \Delta U(t, x) &= \int_0^t \int_D W_H(s, y) \left(\frac{\partial}{\partial t} - \Delta \right) G_{t-s}(x, y) dy ds + W_H(t, x) \\ &= W_H(t, x) \end{aligned}$$

So $U(t, x)$ satisfies (5.1).

Next we study the L^2 -integrability of $U(t, x)$. In the *standard* white noise case ($H_i = \frac{1}{2}$ for all i) the same solution formula (5.4) holds. In this case we see that the solution $U(t, x)$ belongs to $L^2(\mu)$ (μ being the standard white noise measure) iff

$$(5.12) \quad E_\mu[U^2(t, x)] = \int_0^t \int_D G_{t-s}^2(x, y) dy ds < \infty.$$

Now, if $D \subset (-\frac{1}{2}R, \frac{1}{2}R)^d$ and we put $F = [-R, R]^d$,

$$\begin{aligned} \int_0^t \int_D G_{t-s}^2(x, y) ds dy &\sim \int_0^t \int_D s^{-d} \exp\left(-\frac{2y^2}{\delta s}\right) dy ds \\ &\sim \int_0^t \left(\int_{F/\sqrt{s}} s^{-d/2} \exp\left(-\frac{2z^2}{\delta}\right) dz \right) ds. \end{aligned}$$

Hence, if $H_i = \frac{1}{2}$ for all $i = 0, 1, \dots, d$ we have

$$(5.13) \quad E_\mu[U^2(t, x)] < \infty \iff d = 1.$$

Now, consider the *fractional* case. Assume $\frac{1}{2} < H_0 < 1$ and because of (5.13) we may assume that at most one of the indices: H_1, H_2, \dots, H_d is less than $\frac{1}{2}$, say, $0 < H_1 < \frac{1}{2}$ (see also the remark at the end of Section 4). Then

$$(5.14) \quad \begin{aligned} E[U^2(t, x)] &= \int (M_H G_{t-\cdot}(x, \cdot)(s, y))^2 ds dy \\ &\leq C \int_0^t \int_0^t \int_D \int_D \left| \frac{\partial G_{t-s}(x, y)}{\partial y_1} \right| \left| \frac{\partial G_{t-r}(x, z)}{\partial z_1} \right| \\ &\quad \cdot |r - s|^{2H_0 - 2} |y_1 - z_1|^{2H_1} \prod_{i=2}^d |y_i - z_i|^{2H_i - 2} dy_1 \dots dy_d dz_1 \dots dz_d dr ds. \\ &\sim \int_0^t \int_0^t \int_D \int_D r^{-d/2-1} s^{-d/2-1} |x_1 - y_1| |x_1 - z_1| \exp\left(-\frac{|x - y|^2}{\delta r}\right) \exp\left(-\frac{|x - z|^2}{\delta s}\right) \\ &\quad \cdot |r - s|^{2H_0 - 2} |y_1 - z_1|^{2H_1} \prod_{i=2}^d |y_i - z_i|^{2H_i - 2} dy_1 \dots dy_d dz_1 \dots dz_d dr ds. \end{aligned}$$

Note that

$$(5.15) \quad \int_{-\frac{1}{2}R}^{\frac{1}{2}R} \int_{-\frac{1}{2}R}^{\frac{1}{2}R} |x_1 - y_1| |x_1 - z_1| \exp\left(-\frac{|x_1 - y_1|^2}{\delta r} - \frac{|x_1 - z_1|^2}{\delta s}\right) |y_1 - z_1|^{2H_1} dy_1 dz_1 \leq C r s (r^{H_1} + s^{H_1})$$

Using (see [MMV], Inequality (2.1))

$$(5.16) \quad \int_R \int_R |f(x)| |g(y)| |x - y|^{2H-2} dx dy \leq C \|f\|_{L^{1/H}} \|g\|_{L^{1/H}}$$

we have

$$(5.17) \quad \begin{aligned} & \prod_{i=2}^d \int_{-\frac{1}{2}R}^{\frac{1}{2}R} \int_{-\frac{1}{2}R}^{\frac{1}{2}R} \exp\left(-\frac{|x_i - y_i|^2}{\delta r} - \frac{|x_i - z_i|^2}{\delta s}\right) |y_i - z_i|^{2H_i-2} dy_i dz_i \\ & \leq C \prod_{i=2}^d \left\{ \left[\int_{-\frac{1}{2}R}^{\frac{1}{2}R} \exp\left(-\frac{|x_i - y_i|^2}{H_i \delta r}\right) dy_i \right]^{H_i} \left[\int_{-\frac{1}{2}R}^{\frac{1}{2}R} \exp\left(-\frac{|x_i - z_i|^2}{H_i \delta s}\right) dz_i \right]^{H_i} \right\} \\ & \sim (rs)^{\frac{1}{2} \sum_{i=2}^d H_i}. \end{aligned}$$

Substituting (5.17) into (5.14) we have

$$(5.18) \quad E[U^2(t, x)] \leq C \int_0^t \int_0^t (rs)^{-\frac{d}{2} + \frac{1}{2} \sum_{i=2}^d H_i} (r^{H_1} + s^{H_1}) |r - s|^{2H_0-2} dr ds < \infty$$

$$(5.19) \quad \text{if } d/2 - \frac{1}{2} \sum_{i=2}^d H_i < 1$$

$$(5.20) \quad 2 - 2H_0 + 2\left(\frac{d}{2} - \sum_{i=2}^d \frac{1}{2} H_i\right) - H_1 < 2$$

We obtain from this that

$$E[U^2(t, x)] < \infty \quad \text{if } [(2H_0 + H_1) \wedge 2] + \sum_{i=2}^d H_i > d.$$

Now let $1/2 < H_i < 1$ for all $1 \leq i \leq d$. Then

$$(5.21) \quad \begin{aligned} E[U^2(t, x)] &= \int (M_H G_{t-} \cdot(x, \cdot)(s, y))^2 ds dy \\ &\sim \int_0^t \int_0^t \int_D \int_D |G_{t-s}(x, y) G_{t-r}(x, z)| \\ &\quad \cdot |r - s|^{2H_0-2} \prod_{i=1}^d |y_i - z_i|^{2H_i-2} dy_1 \dots dy_d dz_1 \dots dz_d dr ds. \\ &\sim \int_0^t \int_0^t \int_D \int_D r^{-d/2} s^{-d/2} \exp\left(-\frac{|x - y|^2}{\delta r}\right) \exp\left(-\frac{|x - z|^2}{\delta s}\right) \\ &\quad \cdot |r - s|^{2H_0-2} \prod_{i=1}^d |y_i - z_i|^{2H_i-2} dy_1 \dots dy_d dz_1 \dots dz_d dr ds. \end{aligned}$$

By (5.16), we have

$$\begin{aligned}
& \prod_{i=1}^d \int_{-\frac{1}{2}R}^{\frac{1}{2}R} \int_{-\frac{1}{2}R}^{\frac{1}{2}R} \exp\left(-\frac{|x_i - y_i|^2}{\delta r} - \frac{|x_i - z_i|^2}{\delta s}\right) |y_i - z_i|^{2H_i-2} dy_i dz_i \\
& \leq C \prod_{i=1}^d \left\{ \left[\int_{-\frac{1}{2}R}^{\frac{1}{2}R} \exp\left(-\frac{|x_i - y_i|^2}{H_i \delta r}\right) dy_i \right]^{H_i} \left[\int_{-\frac{1}{2}R}^{\frac{1}{2}R} \exp\left(-\frac{p_i |x_i - z_i|^2}{H_i \delta s}\right) dz_i \right]^{H_i} \right\} \\
(5.22) \quad & \sim (rs)^{\frac{1}{2} \sum_{i=1}^d H_i}.
\end{aligned}$$

Substituting (5.22) into (5.21) we have

$$(5.23) \quad E[U^2(t, x)] \leq C \int_0^t \int_0^t (rs)^{-\frac{d}{2} + \frac{1}{2} \sum_{i=1}^d H_i} |r - s|^{2H_0-2} dr ds < \infty$$

$$(5.24) \quad \text{if } 2H_0 + \sum_{i=1}^d H_i > d.$$

We summarize what we have proved:

Theorem 5.1 a) *For any space dimension d there is a unique strong solution $U(t, x) : [0, \infty) \times D \rightarrow (\mathcal{S})^*$ of the fractional heat equation (5.1)–(5.3). The solution is given by*

$$(5.25) \quad U(t, x) = \int_0^t \int_D W_H(s, y) G_{t-s}(x, y) dy ds.$$

It belongs to $C^{1,2}((0, \infty) \times D \rightarrow (\mathcal{S})^) \cap C([0, \infty) \times \bar{D} \rightarrow (\mathcal{S})^*)$.*

b) *If $0 < H_1 < \frac{1}{2}$, $\frac{1}{2} < H_i < 1$ for $i = 0, 2, 3, \dots, d$ and*

$$(5.26) \quad [(2H_0 + H_1) \wedge 2] + \sum_{i=2}^d H_i > d$$

then $U(t, x) \in L^2(\mu)$ for all $t \geq 0$, $x \in \bar{D}$.

c) *If $\frac{1}{2} < H_i < 1$ for $i = 0, 1, \dots, d$ and*

$$(5.27) \quad 2H_0 + \sum_{i=1}^d H_i > d$$

then $U(t, x) \in L^2(\mu)$ for all $t \geq 0$, $x \in \bar{D}$.

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